

# On Perfectly Balanced Boolean Functions

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## Abstract

Perfectly balanced functions were introduced by Sumarokov in [1]. A well known class of such functions are those linear either in the first or in the last variable. We present a novel technique to construct perfectly balanced functions not in the above class.

**Keywords:** Boolean function, perfectly balanced function, function with defect zero.

## 1 Introduction

Let  $\mathbb{N}$  be the set of natural numbers. For  $n \in \mathbb{N}$  let  $V_n = \mathbb{F}_2$  be the  $n$ -dimensional vector space over the field  $\mathbb{F}_2 = GF(2)$ . We use  $\oplus$  for the addition modulo 2. A Boolean function over  $V_n$  is a mapping  $V_n \rightarrow \mathbb{F}_2$ . For any  $n \in \mathbb{N}$  we denote by  $\mathcal{F}_n$  the set of all Boolean functions in variables  $\{x_1, \dots, x_n\}$ . We also identify  $\mathcal{F}_n$  with  $\mathbb{F}_2[x_1, \dots, x_n]/(x_i^2 \oplus x_i, i = 1, \dots, n)$ , the quotient ring of the ring of polynomials with coefficients in  $\mathbb{F}_2$  w.r.t. the ideal generated by the polynomials  $x_i^2 \oplus x_i, i \in \{1, \dots, n\}$ . Then for any  $f \in \mathcal{F}_n$  we have the algebraic normal form

$$f(x) = \bigoplus_{a_1, \dots, a_n \in \mathbb{F}_2} g(a_1, \dots, a_n) x_1^{a_1} \dots x_n^{a_n} = \bigoplus_{a \in V_n} g(a) x^a, \quad (1.1)$$

where  $g \in \mathcal{F}_n$  and  $f \rightarrow g$  is called Möbius Transform of  $\mathcal{F}_n$ . By  $\deg(f)$  we denote the algebraic degree of a function  $f \in \mathcal{F}_n$ .

Let  $f \in \mathcal{F}_n$  and  $i \in \{1, \dots, n\}$ . We use the following notation

$$\deg(f, x_i) = \deg(f(x \oplus e_i) \oplus f(x)) + 1,$$

where  $e_i$ ,  $i = 1, \dots, n$ , are the vectors of the canonical basis of  $V_n$ . If  $\deg(f, x_i) = 1$ , then we say that  $f$  depends linearly on  $x_i$ . The weight  $\text{wt}(f)$  of  $f$  is the number of  $x \in V$  such that  $f(x) = 1$ . A function  $f$  is balanced if  $\text{wt}(f) = \text{wt}(f \oplus 1) = 2^{n-1}$ .

Let  $A = \bigcup_{s=1}^{\infty} \mathbb{F}_2^s$ . By definition, put  $B = \bigcup_{t=n}^{\infty} \mathbb{F}_2^t$ . A Boolean function  $f \in \mathcal{F}_n$  induces a mapping  $B \rightarrow A$  of the form

$$b = (b_1, \dots, b_l) \rightarrow (f(b_1, \dots, b_n), \dots, f(b_{l-n+1}, \dots, b_l)) \quad (1.2)$$

for any  $b \in B$ .

Perfectly balanced functions (i.e., Boolean functions  $f$  such that the mapping (1.2) is onto) were introduced by Sumarokov in [1]. A well known class of such functions (cf. [2]) consists of all functions that are linear either in the first or in the last variable. The aim of this paper is to develop a novel technique to construct perfectly balanced functions not in the above class.

## 2 Basic definitions

Let  $f \in \mathcal{F}_n$  and  $m \in \mathbb{N}$ . Consider the system of equations

$$f(x_s, x_{s+1}, \dots, x_{s+n-1}) = y_s, \quad s = 1, 2, \dots, m, \quad (2.1)$$

where  $x = (x_1, \dots, x_{m+n-1}) \in V_{m+n-1}$ ,  $y = (y_1, \dots, y_m) \in V_m$ . In vectorial form this system can be written as follows

$$y = f_m^*(x),$$

where

$$\begin{aligned} f_m^*(x_1, x_2, \dots, x_{m+n-1}) \\ = (f(x_1, \dots, x_n), f(x_2, \dots, x_{n+1}), \dots, f(x_m, \dots, x_{m+n-1})). \end{aligned} \quad (2.2)$$

For any  $f \in \mathcal{F}_n$  and any  $m \in \mathbb{N}$  consider a set

$$J(f, m) = \{y \in V_m \mid \forall x \in V_{m+n-1} f(x) \neq y\}. \quad (2.3)$$

Denote by  $\text{Def}_m(f)$  the cardinality of  $J(f, m)$ .

**Definition 2.1** ([1]). A function  $f \in \mathcal{F}_n$  is said to have defect zero iff  $\text{Def}_m(f) = 0$  for any  $m \in \mathbb{N}$ .

It is easy to see ([1]) that  $f \in \mathcal{F}_n$  has defect zero if  $\deg(f, x_1) = 1$  or  $\deg(f, x_n) = 1$ . Let

$$\mathcal{L}_n = \{f \in \mathcal{F}_n \mid \deg(f, x_1) = 1\}$$

and

$$\mathcal{R}_n = \{f \in \mathcal{F}_n \mid \deg(f, x_n) = 1\}.$$

**Definition 2.2** ([1]). A function  $f \in \mathcal{F}_n$  is called perfectly balanced iff

$$\sharp(f_m^*)^{-1}(y) = 2^{n-1}$$

for any  $m \in \mathbb{N}$  and for every  $y \in V_m$  ( $\sharp M$  denotes the cardinality of the set  $M$ ).

Let  $\mathcal{E}_n$  denote the set of all perfectly balanced functions in  $\mathcal{F}_n$ . From Definition 2.2 it is easy to see that a perfectly balanced function  $f \in \mathcal{F}_n$  is balanced, i.e.,  $\text{wt}(f) = 2^{n-1}$ . It follows immediately that  $\sharp\mathcal{E}_n/2^{2^n} \rightarrow 0$  as  $n \rightarrow \infty$ .

### 3 Preliminaries

**Theorem 3.1** ([1]). *A Boolean function has defect zero iff it is perfectly balanced.*

Denote by  $\mathcal{D}_n$  the set of Boolean functions in  $\mathcal{E}_n$  such that

$$\deg(f, x_1) \geq 1, \quad \deg(f, x_n) \geq 1.$$

Sumarokov [1] developed a technique to construct functions in  $\mathcal{D}_n \setminus (\mathcal{L}_n \cup \mathcal{R}_n)$  was developed.

**Example 3.2** ([1]). A Boolean function

$$f(x_1, x_2, x_3, x_4) = x_1x_2 \oplus x_2 \oplus x_3 \oplus x_1x_2x_4 \oplus x_2x_4 \oplus 1$$

is a perfectly balanced function in  $\mathcal{D}_4 \setminus (\mathcal{L}_4 \cup \mathcal{R}_4)$ .

Furthermore Sumarokov [1] proved some upper bounds on  $m$  for functions of nonzero defect and defined the following mappings  $\gamma_0, \gamma_1, \gamma_2$  from  $\mathcal{F}_n$  onto  $\mathcal{F}_n$  such that  $\gamma_i(\mathcal{E}_n) = \mathcal{E}_n$ ,  $i = 1, 2, 3$ :

- (1)  $\gamma_0: f(x_1, \dots, x_n) \rightarrow f(x_1, \dots, x_n) \oplus 1$ ;
- (2)  $\gamma_1: f(x_1, \dots, x_n) \rightarrow f(x_1 \oplus 1, \dots, x_n \oplus 1)$ ;
- (3)  $\gamma_2: f(x_1, \dots, x_n) \rightarrow f(x_n, \dots, x_1)$ .

For certain applications it is interesting to investigate conditions under which the distribution of the right-hand side of (2.1) is uniform provided that the distribution of the random vector  $X_m = (x_1, \dots, x_{m+n-1})$  is uniform.

**Theorem 3.3** ([3]). *Let  $\{X_m = (x_1, \dots, x_{m+n-1})\}_{m=1}^\infty$  be a sequence of random variables, where  $X_m$  is distributed uniformly over  $V_{m+n-1}$ . Then the random variable  $Y_m = f_m^*(X_m)$  is distributed uniformly for any  $m \in \mathbb{N}$  iff the function  $f$  is perfectly balanced.*

## 4 Main result

For any  $k \in \mathbb{N}$  and any  $l \in \mathbb{N}$  consider a mapping  $\Xi_{k,l}: \mathcal{F}_k \times \mathcal{F}_l \rightarrow \mathcal{F}_{k+l-1}$  of the form

$$\Xi_{k,l}(f, g) = f[g] = h \in \mathcal{F}_{k+l-1}, f \in \mathcal{F}_k, g \in \mathcal{F}_l,$$

where

$$\begin{aligned} h(x_1, \dots, x_{k+l-1}) &= f[g](x_1, \dots, x_{k+l-1}) \\ &= f(g(x_1, \dots, x_k), g(x_{k+1}, \dots, x_{k+l-1})). \end{aligned}$$

Our main result is the next theorem.

**Theorem 4.1.** *Let  $f \in \mathcal{F}_k$ ,  $g \in \mathcal{F}_l$ . A Boolean function  $h = f[g] \in \mathcal{F}_{k+l-1}$  is perfectly balanced iff both functions  $f$  and  $g$  are perfectly balanced.*

*Proof.* Let  $f$  and  $g$  be perfectly balanced functions and  $m$  be any natural number. Then for any vector  $z = (z_1, \dots, z_m) \in V_m$  we have  $\sharp(f_m^*)^{-1}(z) = 2^{k-1}$ . Furthermore for every vector  $y = (y_1, \dots, y_{m+k-1}) \in (f_m^*)^{-1}(z)$  we have  $\sharp(g_{m+k-1}^*)^{-1}(y) = 2^{l-1}$ . It now follows that

$$\begin{aligned} \sharp(h_m^*)^{-1}(z) &= \sharp(f[g]_m^*)^{-1}(z) \\ &= \sum_{y \in \sharp(f_m^*)^{-1}(z)} \sharp(g_{m+k-1}^*)^{-1}(y) = 2^{k+l-2} = 2^{(k+l-1)-1}, \end{aligned}$$

for any  $m \in \mathbb{N}$  and any  $z \in V_m$ , i.e. a function  $h \in \mathcal{F}_{k+l-1}$  is perfectly balanced.

Let the function  $h = f[g] \in \mathcal{F}_{k+l-1}$  be perfectly balanced. Assume the contrary, namely, that either  $f$  or  $g$  is not perfectly balanced. First assume that  $f$  is not perfectly balanced. By Theorem 3.1,  $f$  is not a function of defect zero. Then there exist a natural number  $m$  and a vector  $z = (z_1, \dots, z_m) \in V_m$  such that  $z \in J(f, m)$ . Therefore we have  $z \in J(f[g], m)$ , i.e.,  $f[g]$  is not a function of defect zero. By Theorem 3.1,  $f[g]$  is not perfectly balanced. This contradiction proves that  $f$  is perfectly balanced.

Now, assume that  $g$  is not perfectly balanced. Then there exist a natural number  $r$  and a vector  $y^* = (y_1^*, \dots, y_r^*) \in V_r$  such that  $\sharp(g_r^*)^{-1}(y^*) = 2^{l-1} + \alpha$ , where  $0 < \alpha \leq 2^{l-1}$ . Using the vector  $y^*$ , we construct a set  $M_{r,t}$ ,  $t = 1, 2, \dots$  of vectors in  $V_{r(t+1)+(l-1)t}$  of the form

$$y = (y_1^*, \dots, y_r^*; y_{r+1}, \dots, y_{l+r-1}; y_1^*, \dots, y_r^*; \dots; y_1^*, \dots, y_r^*; y_{tr+(t-1)(l-1)}, \dots, y_{tr+t(l-1)}; y_1^*, \dots, y_r^*),$$

where components of  $y$  not asterisked are arbitrary. It follows easily that  $\sharp M_{r,t} = (2^{l-1})^t$ . Using the definition of the set  $M_{r,t}$ , one can show that for any  $y \in M_{r,t}$  with  $(g_{r(t+1)+(l-1)t}^*)^{-1}(y) \neq \emptyset$ , the next inclusion holds:

$$(g_{r(t+1)+(l-1)t}^*)^{-1}(y) \subseteq \underbrace{(g_r^*)^{-1}(y^*) \times \dots \times (g_r^*)^{-1}(y^*)}_{t+1}.$$

Furthermore it is clear that

$$g_{r(t+1)+(l-1)t}^* \left( \underbrace{(g_r^*)^{-1}(y^*) \times \dots \times (g_r^*)^{-1}(y^*)}_{t+1} \right) \subseteq M_{r,t}.$$

Let  $\mu_t$  denote an expected number of vectors in the set  $\underbrace{(g_r^*)^{-1}(y^*) \times \dots \times (g_r^*)^{-1}(y^*)}_{t+1}$  per vector of the set  $M_{r,t}$ :

$$\mu_t = \frac{2^{l-1} + \alpha}{(2^{l-1})^t} = 2^{l-1} \left( 1 + \frac{\alpha}{2^{l-1}} \right)^{t+1}.$$

Since  $(1 + \alpha/2^{l-1}) > 1$ , it follows that there exists a natural number  $t_0$ , such that  $\mu_{t_0} > 2^{(k+l-1)-1}$ .

Consequently there exists a vector  $y \in M_{r,t_0}$  with property

$$\#(g_{r(t_0+1)+(l-1)t_0}^*)^{-1}(y) > 2^{(k+l-1)-1}. \quad (4.1)$$

Let  $z = f_{r(t_0+1)+(l-1)t_0-k+1}^*(y)$ . Using (4.1) we get

$$\#(f[g]_{(t_0+1)(r+l-1)-k+1}^*)^{-1}(z) > 2^{(k+l-1)-1},$$

i.e., a function  $f[g]$  is not perfectly balanced. This contradiction proves the theorem.  $\square$

Using Theorem 4.1, we can construct perfectly balanced functions in  $\mathcal{D}_n \setminus (\mathcal{L}_n \cup \mathcal{R}_n)$ .

**Example 4.2.** Let  $f(x_1, x_2, x_3) = x_1 + x_2x_3 \in \mathcal{L}_3$  and  $g(x_1, x_2, x_3) = x_1x_2 \oplus x_3 \in \mathcal{R}_3$ . Then

$$\begin{aligned} h(x_1, x_2, x_3, x_4, x_5) &= f(g(x_1, x_2, x_3), g((x_2, x_3, x_4), g(x_3, x_4, x_5))) \\ &= x_1x_2 \oplus x_3 \oplus x_2x_3x_4 \oplus x_2x_3x_5 \oplus x_3x_4 \oplus x_4x_5 \in \mathcal{D}_5 \setminus (\mathcal{L}_5 \cup \mathcal{R}_5). \end{aligned}$$

## References

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